

User Manual

for

DA14000-12-4M-PCI DA14000-12-16M-PCI

1 Channel, 4.0 GSPS, 12-Bit, PCI Arbitrary Waveform Generator Card

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1 GENERAL INFORMATION

1.1 Introduction

The DA14000 is a (1) Channel, 12-bit, 4.0 GigaSample/sec Arbitrary Waveform Generator on a single short-sized PCI card. It comes standard with following general features:

- Standard Internal Fixed Clock at 4.0 GSPS (external at 4.0 GHz, 2.0 GHz, 1.0 Ghz, 500 MHz)
- (1) Channel Analog Output, 12-bit Vertical Resolution
- (2) TTL Output Marker
- Programmable Segment Size from 128 Data Words to full memory
- Programmable Number of Segments up to 32K
- External AC clock and External TTL/ECL trigger input

The analog output consist of (1) 50 ohm SMA output, AC-Coupled. To provide maximum flexibility and performance to the user, [the outputs come unfiltered. An appropriate low pass filter is generally added in-line for a particular application and can be bought from companies like Mini-Circuits or can be ordered and/or custom made directly from Chase Scientific.](#)

The DA14000 has TTL/ECL input triggering capability that allows a segment or segments of data to be output only after a trigger is present.

1.2 References

PCI Local Bus Specification, Rev. 2.1, June 1st, 1995. For more information on this document contact:
PCI Special Interest Group
P.O Box 14070
Portland, OR 97214

Phone: 503-619-0569
FAX: 503-644-6708
<http://www.pcisig.com>

1.3 Deliverables

1.3.1 Software

The DA14000 comes with 32-bit DLL drivers for **Windows 98/ME/NT4/2000/XP/Vista/7**. The user can download them from our web site at “www.chase2000.com”. Call Chase Scientific for for the latest information on drivers for other operating system platforms such as Linux and 64-bit versions.

Windows drivers are provided as a Dynamic Link Library (*.DLL) which is compatible with most 32-bit and 64-bit windows based development software including Microsoft C/C++, Borland C/C++, and Borland Delphi. This DLL uses the “**cdecl**” calling convention for maximum compatibility. It automatically provides the interface to the low level system drivers “**Windrvr6.sys**” for Windows 98/ME/NT4/2000/XP and “**SIPLXWDF.sys**” for Windows 7 32/64-bit.

1.3.2 Hardware

The DA14000 hardware consists of a single short PCI compliant card. The card is shipped with this manual which includes complete hardware and software descriptions.

1.3.3 Checklist

Item #	Qty	Part Number	Description
1	1	DA14000-12-1M-PCI	4.0 GSPS, Arbitrary Waveform Generator, short PCI card.
2	1	DA14000 Drivers	Optional Mini-CDR with Dynamic Link Libraries for Windows 95/98/ME/NT4/2000/XP/Vista/7. Includes examples and manual. Otherwise download from web site at: www.chase2000.com

1.4 Product Specification

(all specifications are at 25 °C unless otherwise specified)

SPECIFICATIONS

Parameter	Conditions	Typical Values unless otherwise indicated
Analog Outputs		
Number of Outputs		(1) 50 ohm SMA outputs
Output Coupling		AC coupling through 0.1uF capacitor (50 ohm source impedance)
Vertical Resolution		12 bits (1 part in 4096)
Amplitude	4.0 GS/s	0.6Vpp +/-3% typical, single ended into 50 ohms.
Rise Time (20% to 80%)	No Filters	160 psec typical into 50 ohms
Fall Time (80% to 20%)	No Filters	160 psec typical into 50 ohms
Clock Jitter	4.0 GS/sec	Less than 10 psec RMS at 4 GHz
Trigger Delay	4.0 GS/sec	TBD
SFDR		
Fout < 1.3 GHz	4.0 GS/sec	< -40 dB Typical
Fout = 660- 800 MHz	4.0 GS/sec	< -45 dB Typical

Internal Clock Rate		
Frequency Range		4.0 GHz Fixed
Resolution		N/A
Stability	T=0°C – 70°C	120 ppm
Memory		
Waveform Size	Standard	4 MWords / 16 MWords x 12-bits (-4M-PCI, -16M-PCI)
# of User Segments		1 to 16K segments
Segment Size Range		128 Samples up to total memory in 128 Sample increments
Digital Outputs		
(2) TTL Markers		Fclk/4 resolution
Digital Inputs		
External Clk input		50 ohm SMA input AC coupled. Can only use the following frequencies: 4.0 GHz, 2.0 Ghz, 1.0 GHz, and 500 MHz. Adjust jumpers U34 as needed.
TTL Trigger input		Used to initiate any memory segment programmed for that purpose.

ENVIRONMENTAL

Parameter	Typical Values unless otherwise stated
Temperature	
Operating	0 to 70 degrees C standard
Non-Operating	-40 to +85 degrees C extended
Humidity	
Operating	20% to 80%
Non-Operating	5% to 95%
Power	
+5V	TBD
+3.3V	TBD
+12V	TBD
-12V	N/A
Size	
DA14000	(1) Short PCI Card

1.5 Option Summary

OPTION SUMMARY

Option Name	Description
TBD	TBD

1.6 Technical Support / Software Updates

For technical support:

Email:	techsupport@chase2000.com
Phone:	360-221-8455
Fax:	360-221-8457
Mail:	Chase Scientific Company P.O. Box 1487 Langley, WA 98260

For software updates:

Email:	techsupport@chase2000.com
Web:	http://www.chase2000.com

1.7 Warranty

Chase Scientific Company (hereafter called Chase Scientific) warrants to the original purchaser that its DA14000, and the component parts thereof, will be free from defects in workmanship and materials for a period of ONE YEAR from the date of purchase.

Chase Scientific will, without charge, repair or replace at its option, defective or component parts upon delivery to Chase Scientific's service department within the warranty period accompanied by proof of purchase date in the form of a sales receipt.

EXCLUSIONS: This warranty does not apply in the event of misuse or abuse of the product or as a result of unauthorized alterations or repairs. It is void if the serial number is altered, defaced or removed.

Chase Scientific shall not be liable for any consequential damages, including without limitation damages resulting from loss of use. Some states do not allow limitation or incidental or consequential damages, so the above limitation or exclusion may not apply to you.

This warranty gives you specific rights. You may also have other rights that vary from state to state.

Chase Scientific warrants products sold only in the USA and Canada. In countries other than the USA, each distributor warrants the Chase Scientific products that it sells.

NOTICE: Chase Scientific reserves the right to make changes and/or improvements in the product(s) described in this manual at any time without notice.

2 HARDWARE DESCRIPTION

2.1 Introduction

The DA14000 hardware consists of the following major connections:

- (1) Normal, 4.0Gigasamples/second, 12-bit analog output (SMA)
- (1) PECL/Sinewave Clock Input, 500MHz, 1.0 GHz, 2.0 GHz, 4.0 GHz ONLY (AC coupled)
- (1) TTL Trigger input (SMA)
- (2) TTL Outputs Markers (SMA)

2.2 Block Diagram (Temporary Placeholder)

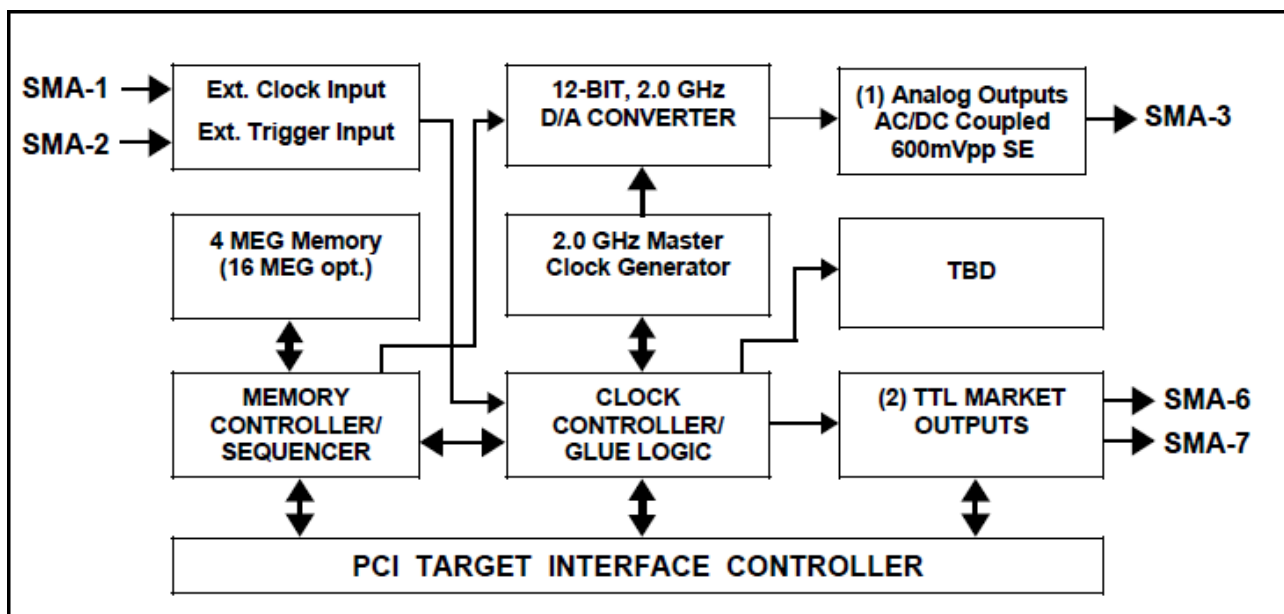


Figure 1 – Block Diagram (Temporary Placeholder)

2.3 Board Drawing

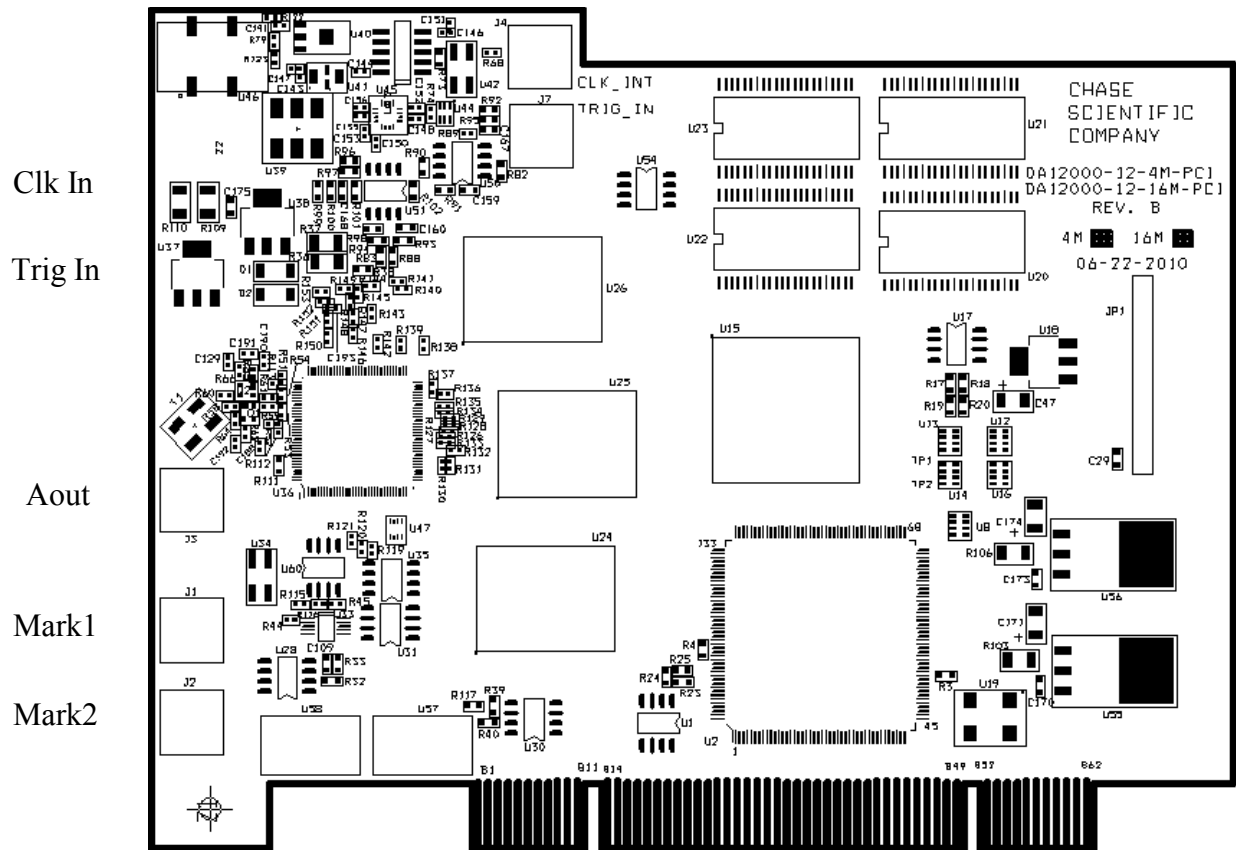


Figure 2 – Board Layout

2.4 External Clock Jumper Configurations

U70 (ext/int clock select)

Orientation for shunt is top-to-bottom. Left position uses internal clock while right position uses external clock.

U34 (phase adjust)

Orientation for shunt is left-to-right. Default position performed at factory is for 4.0 GHz operation only. Other frequencies may require different selections. The purpose of this adjustment is to place the SRAM data in the center of the internal D/A clock.

2.5 PCI Memory Allocation

DA14000 on-board memory is mapped automatically when a PCI 2.1 (or newer) motherboard powers up. If the DA14000 has 4 MegaSamples of memory, then the motherboard will allocate 8 Megabytes of memory. Once installed, the DA14000 software drivers will find the board or boards without the user changing any jumpers or worrying about addressing.

3 THEORY OF OPERATION

3.1 Introduction

Although the DA14000 is primarily comprised of a **Segment Sequencer** (or memory manager) and a 4:1 **High Speed Multiplexor**, it's how the software interacts with the hardware that makes it work. The following sections should provide enough operational theory for better understanding when using the software drivers.

3.2 Downloading and Outputting User Data to the DA14000

The DA14000 QDR2 SRAM memory IC's contain the user's waveform data while the special command codes that run the Segment Sequencer are stored in separate SRAM. The Segment Sequencer reads these codes to determine where and when to jump to another segment, how many times to loop, when to wait for a trigger, and when to shut down. This is the heart of the DA14000 memory management.

Downloading a Single User Waveform (single segment) into memory is performed by simply calling `da14000_CreateSingleSegment(DWORD CardNum, DWORD NumPoints, DWORD NumLoops, PVOID UserArrayPtr, DWORD TrigEn)`. The user must be sure to pass the size of the waveform (`NumPoints`), the number of times to repeat the waveform (`NumLoops`), a pointer variable pointing to the user array containing the data (`UserArrayPtr`), and finally, whether the segment will be self triggered or triggered by an external signal (`TrigEn`).

Downloading Multiple Linked Waveform Segments is performed by calling `da14000_CreateSegments(DWORD CardNum, DWORD NumSegments, PVOID PtrToSegmentsList)`. This function call requires the user to create a structure containing all the critical information on the segments that the user wants to download. The actual structure for each segment looks like the following:

```
typedef struct
{
    DWORD    SegmentNum;    // Current Segment Number
    PVOID    SegmentPtr;   // Pointer to current user segment
                                // ==> elements of one dimensional array must
                                // be of type DWORD
    DWORD    NumPoints;    // Number of points in segment (must be multiple of 128)
    DWORD    NumLoops;     // Number of times to repeat segment (applies
                                // to next segment)
    DWORD    BeginPadVal;  // Reserved for future use.
    DWORD    EndingPadVal; // Reserved for future use.
    DWORD    TrigEn;       // If > 0 then wait for trigger before going to
                                // next segment.
    DWORD    NextSegNum;   // Next segment to jump to after completion
                                // of current segment activities
} SegmentStruct;
```

The user must create an array of these segments and pass the pointer (`PtrToSegmentsList`) to the function call.

After the appropriate waveform data has been downloaded to the DA14000, `da14000_SetTriggerMode()` is enabled and the output begins.

4 SOFTWARE DRIVERS

4.1 Introduction

Our primary objective in designing software drivers is to get the user up and running as quickly as possible. While the details on individual function calls are listed in sections 4.3.x, the programming examples in section 4.4.x will show you how to include them into your programs. Please note that function calls are the same whether you are calling them under Windows 98, ME, NT4, 2000, or XP.

4.2 Driver Installation

*****IMPORTANT NOTE: Most files/directories use DA12000 instead of DA14000 because the software has been merged and works for both. It may be a little confusing at first, but bear with us until we come up with a more generic nomenclature. The purpose of the merge is to allow us to manage both products with one code base. Since the boards are 95% software identical, it makes sense to make improvements to both products at the same time.**

4.2.1 Windows 98 / ME / NT4

- 1) Do not install DA14000 card at this time.
- 2) UnZip all files into directory "C:\temp\da12000\" (create directories if needed) You can move and/or copy the files later to a directory of your choice.
- 3) Run da12000_Register_Win98_ME_NT4.bat. This will copy the Kernel driver windrvr6.sys to "c:\<windir>\system32\drivers\" directory and will register the Kernel driver in the Windows Registry so that it starts up each time the computer is rebooted.
- 4) Power off computer. Insert DA14000 card. Power up computer.
- 5) When OS asks for Driver File point to "da12000_PCI.inf". If OS does not ask for file, then check hardware configuration and update if not listed properly under "Jungo" in Device Manager (see below).

To check to see which driver is installed, do the following:

=> Control Panel
=> System
=> Hardware
=> Device Manager
=> **Jungo**
 DA12000_PCI (Both this and WinDriver below should be present)
 WinDriver

If you see another driver in place of "DA12000_PCI", then right click the first device under Jungo and click properties. Update the driver by pointing to "DA12000_PCI.inf". You may have to go through a series of menus.

4.2.2 Windows 2000 / XP

- 1) Do not install DA14000 card at this time.

- 2) UnZip all files into directory "C:\temp\da12000\" (create directories if needed) You can move and/or copy the files later to a directory of your choice.
- 3) Run da12000_Register_Win2000_XP.bat. This will copy the Kernel driver windrvr6.sys to "c:\<windir>\system32\drivers\" directory and will register the Kernel driver in the Windows Registry so that it starts up each time the computer is rebooted.
- 4) Power off computer. Insert DA12000 card. Power up computer.
- 5) When OS asks for Driver File point to "da12000_PCI.inf". If OS does not ask for file, then check hardware configuration and update if not listed properly under "Jungo" in Device Manager (see below).

To check to see which driver is installed, do the following:

```
=> Control Panel
    => System
        => Hardware
            => Device Manager
                => Jungo
                    DA12000_PCI (Both this and WinDriver below should be present)
                    WinDriver
```

If you see another driver in place of "DA12000_PCI", then right click the first device under Jungo and click properties. Update the driver by pointing to "DA12000_PCI". You may have to go through a series of menus.

4.2.3 Windows Vista / Windows 7

Assumption: First time install.

First install the board, then when it asks you for the driver location just point to the "SIPLXWDF.inf" file. It may take up to 20 seconds or so. Please note that you must have administrative privileges to do this. Also, to run a program on Win7 which accesses hardware you will have to assign "administrative privileges" to the executable file (right-click).

Please refer all questions to: techsupport@chase2000.com

4.3 Function Calls

4.3.1 C Header File for DLL

```
//-----
#define da12000_dll64_importH
#define da12000_dll64_importH
//-----

//-----
// USER ROUTINES
```

```

//-----

#define IMPORT extern "C" __declspec(dllimport)

// DA12000 prototypes
IMPORT DWORD dal2000_CountCards(void);
IMPORT DWORD dal2000_Open(DWORD CardNum);
IMPORT DWORD dal2000_Close(DWORD CardNum);

IMPORT void dal2000_SetClock(DWORD CardNum, DWORD Frequency);

IMPORT void dal2000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol);
IMPORT void dal2000_SetSoftTrigger(DWORD CardNum);
IMPORT void dal2000_SetOffset(DWORD CardNum, DWORD ChanNum, int Mode, int Offset);

IMPORT void dal2000_CreateSingleSegment(DWORD CardNum, DWORD ChanNum, DWORD NumPoints, DWORD
NumLoops, PVOID UserArrayPtr, DWORD TrigEn);
IMPORT void dal2000_CreateSegments(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList);
IMPORT void dal2000_UpdateSegmentCmds(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList);

//-----
// USER ROUTINES (DA14000 calls really calls to same DA12000 DLL)
//-----

void dal4000_CountCards() {return dal2000_CountCards();}
void dal4000_Open(DWORD CardNum) {return dal2000_Open(CardNum);}
void dal4000_Close(DWORD CardNum) {return dal2000_Close(CardNum);}

void dal4000_SetClock(DWORD CardNum, DWORD Frequency) {
    dal2000_SetClock(CardNum, Frequency);
}

void dal4000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol) {
    dal2000_SetTriggerMode(CardNum, Mode, ExtPol);
}

void dal4000_SetSoftTrigger(DWORD CardNum) {
    dal2000_SetSoftTrigger(CardNum);
}

void dal4000_SetOffset(DWORD CardNum, DWORD ChanNum, int Mode, int Offset) {
    dal2000_SetOffset(CardNum, ChanNum, Mode, Offset);
}

void dal4000_CreateSingleSegment(DWORD CardNum, DWORD ChanNum, DWORD NumPoints, DWORD NumLoops,
PVOID UserArrayPtr, DWORD TrigEn) {
    dal2000_CreateSingleSegment(CardNum, ChanNum, NumPoints, NumLoops, UserArrayPtr, TrigEn);
}

void dal4000_CreateSegments(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList) {
    dal2000_CreateSegments(CardNum, ChanNum, NumSegments, PtrToSegmentsList);
}

void dal4000_UpdateSegmentCmds(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList) {
    dal2000_UpdateSegmentCmds(CardNum, ChanNum, NumSegments, PtrToSegmentsList);
}

#endif

```

4.3.2 Function Call Descriptions / Usage

4.3.2.1 da14000_CountCards()

Description

Returns number of DA14000 cards present on computer.

Declaration

```
DWORD da14000_CountCards(void);
```

Parameters

none

Return Value

Returns with an encoded value which represents the number of DA14000.

Return Values:

- 1-4: Number of DA14000 boards detected.
- 0: Indicates that no boards were found but that drivers are working properly.
- 13: Software drivers are not installed properly.
working correctly. "13"

Example

```
DWORD Num_da14000_Boards = da14000_Open() & 0x3;
```

4.3.2.2 da14000_Open()

Description

Loads the DA14000 software drivers and sets the DA14000 board to its default state.

Declaration

```
DWORD da14000_Open(DWORD CardNum);
```

Parameters

CardNum: 1 <= CardNum <= 4

Return Value

Returns with error code. A "0" means everything is fine. See below for details for other values.

Return Values:

- 0: Opened Windriver Successfully and DA14000 Card Found Successfully
- 1: Opened Windriver Successfully, but NO DA14000 CARDS FOUND
- 2: Opened Windriver Successfully, Card found, but unable to open.
- 3: Opened Windriver Successfully, Board already open.
- 6: Card number exceeds number of cards.
- 13: FAILED TO OPEN Windriver Kernel Driver

Example

```
DWORD OpenErrorCode = da14000_Open(1); // Opens Board Number 1 and stores value.
```

4.3.2.3 da14000_Close()

Description

Closes DA14000 drivers. Should be called after finishing using the driver. However, if no other software uses the “windrv.xxx” (usual situation), then there is no need to close it until user is ready to completely exit from using their main software program which calls “windrv.xxx”. If the user is loading the “windrv.xxx” dynamically (during run time), then they should close before unloading the driver.

Declaration

```
DWORD da14000_Close(DWORD CardNum);
```

Parameters

CardNum: 1 <= CardNum <= 4

Return Value

Returns with error code. A "0" means everything is fine. See below for details for other values.

Return Values:

- 0: Closed Windriver Successfully for DA14000 card requested.
- 5: DA14000 Card Already Closed for card requested.
- 13: FAILED TO ACCESS Windriver Kernel Driver

Example

```
DWORD CloseErrorCode = da14000_Close(1);
```

4.3.2.4 da14000_SetClock() [Not Used]

Description

Sets the Digital to Analog converter clock rate. This function does nothing (placeholder) at this time on the DA14000. The card is fixed at 4.0 GSPS. There are jumpers on the PCB to allow for external clock features (see section 2.4).

Declaration

n/a

Parameters

n/a

Return Value

none

Example

n/a

4.3.2.5 da14000_SetTriggerMode()

Description

Sets triggering modes. This command should be called (using mode=0) just after the driver is opened to initialize internal hardware registers before calling any other routines. This function also selects whether board is in triggered mode or not and polarity of external TTL triggered signal.

Declaration

```
void da14000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol);
```

Parameters

CardNum: 1 <= CardNum <= 4

Mode:

- 0: Shuts down all output operations. Asynchronously resets RAM address counter and repeat counters to zero.
- 1: Used for starting single segment operation for segment created with “da14000_CreateSingleSegment()”. Repeats indefinitely until mode set back to 0. External or “soft” trigger has no effect in this mode. Also works for “da14000_CreateSegments()”, but any segments specified as triggered will immediately jump to next segment (no trigger required).
- 2: Sets up first segment for external or “soft” trigger mode. Individual segment(s) created as triggered will wait until external or soft trigger has occurred. If segment was created not to be triggered, then segment will follow previous segment in a continuous fashion (no trigger needed). See da14000_CreateSegments for more information on multi-segment functioning.

ExtPol:

Not Used at time manual was written/updated.

Return Value

none

Example

```
da14000_SetTriggerMode(1,2,0); // First segment will wait for trigger before
                               // running.
```

4.3.2.6 da14000_SetSoftTrigger() [TBD]**Description**

Emulates external triggering in software. Since this function actually toggles polarity of external input signal, it is “ORed” with external signal.

Declaration

```
void da14000_SetSoftTrigger(DWORD CardNum);
```

Parameters

none

Return Value

none

Example

```
da14000_SetSoftTrigger(1); // Initiates software trigger on Card Number 1
```

4.3.2.7 da14000_SetMarkers() [See notes below]**Description**

This function is not used. Add 1 to waveform data BIT12 for Marker #1, BIT13 for Marker # 2 . Use modulo 4 for DA12000 and modulo 8 for DA14000.

4.3.2.8 da14000_CreateSingleSegment()

Description

Creates a single segment in memory. The user determines the size of the array and whether the segment is started automatically or waits for an external input trigger. After creating a single segment waveform, the user must call SetTriggerMode() to turn on/off output waveforms.

See "[da14000_CreateSegments\(\)](#)" for generating multiplied segments.

Declaration

```
void da14000_CreateSingleSegment(DWORD CardNum,
                                DWORD ChanNum,
                                DWORD NumPoints,
                                DWORD NumLoops,
                                PVOID UserArrayPtr,
                                DWORD TrigEn);
```

Parameters

CardNum: 1 <= CardNum <= 4

ChanNum: 0x01, 0x02, 0x04, 0x08 for channels 1,2,3, and 4 [DA14000]

NumPoints: 0 <= NumPoints <= (MaxMem-128)
 [*** MUST BE MULTIPLE OF 64 for DA12000 ***]
 [*** MUST BE MULTIPLE OF 128 for DA14000 ***]

NumLoops: Set to 0 (other values not available) [0 = Continuous]

UserArrayPtr: Pointer to user array of WORD for WinXP/7-32 and DWORD for Win7-64.

TrigEn: High enables external trigger (must also set da14000_SetTriggerMode to triggered)

Return Value

None.

Example

```
da14000_CreateSingleSegment(1, // Card Number 1
                             1, // Channel 1
                             128, // 128 Words contained
                             0, // Loops continuously
                             UserArrayPointer, // Pointer to user data (DWORD)
                             0); // External trigger not enabled
```

4.3.2.9 da14000_CreateSegments()

Description

Creates any number of segments up to the size of memory. Each segment can be programmed for repeat counts up to 16K and can jump to any other segment. See below for data structures for creating user segments. User must provide the correct array structures and pass a pointer to it along with how many sequential segments are desired to be used.

After creating a complete waveform, the user must call SetTriggerMode() to turn on/off output waveforms. We also highly recommend using 128 sample pad (e.g. value=2048) at beginning and end of waveform to give the cleanest start/stop waveforms.

Declaration

```
void da14000_CreateSegments(DWORD CardNum,
                           DWORD ChanNum,
                           DWORD NumSegments,
                           PVOID PtrToSegmentsList);
```

Parameters

```
CardNum:      1 <= CardNum <= 4
ChanNum:      0x01 (only valid number)
```

```
NumSegments:  Number of segment structures (see below) which user has
                defined and wants to use.
```

```
PtrToSegmentsList: Pointer to user array with each element with structure
                    defined as shown below.
```

```
typedef struct
{
    DWORD    SegmentNum;    // Current Segment Number
    PVOID    SegmentPtr;   // Pointer to current user segment
                                // *** elements of one dimensional array must
                                // be of type WORD for WinXP/7-32 and DWORD for Win7-64

    DWORD    NumPoints;    // Number of points in segment
                                // [ *** MUST BE MULTIPLE OF 64 for DA12000 *** ]
                                // [ *** MUST BE MULTIPLE OF 128 for DA14000 *** ]

    DWORD    NumLoops;     // Number of extra times to repeat current segment
    DWORD    BeginPadVal;  // [Reserved for future use]
    DWORD    EndingPadVal; // [Reserved for future use]
    DWORD    TrigEn;      // If > 0 then wait for trigger before going to
                                // next segment.
    DWORD    NextSegNum;   // Next segment to jump to after completion
                                // of current segment activities
} SegmentStruct;
```

**** Note that a segment is determined to be a triggered segment by the previous segment. So setting Segment 5 as triggered will stop the sequence after Segment 5 has executed and will wait for trigger event before "NextSegNum" is started.

The first segment is a special case and is determined by default as a triggered type if SetTriggerMode() is set to "mode=2". The user in this case may use an external trigger or a "soft" trigger to initiate the output process.

Return Value:

none.

Example

```
// 4 Segments Data and beginning/ending Pad Segments

// Multiple Segment Structure
typedef struct                // Creates Type instead of variable
{
    DWORD    SegmentNum;    // Current Segment Number
    PVOID    SegmentPtr;   // Pointer to current user segment
                                // ** Elements of one diminsional array must be type
                                // WORD for WinXP/7-32 and DWORD for Win7-64
    DWORD    NumPoints;    // Number of points in segment
```

```

        DWORD    NumLoops;           // Number of loops desired before going to next segment
        DWORD    BeginPadVal;       // Pad value for beginning of triggered segment
        DWORD    EndingPadVal;      // Pad value for ending of triggered segment
        DWORD    TrigEn;            // If > 0 then wait for trigger before going
                                    // to next segment

        DWORD    NextSegNum;        // Next segment to jump to after completion
                                    // of current segment activities (0xFFFF
                                    // causes shutdown)
    } SegmentStruct;
//

    da12000_SetTriggerMode(1,0,0);           // Initialize

// ##### BOARD NUMBER 1 ##### //

// Create Array for SegmentsList_Brd1 and Segments
SegmentStruct SegmentsList_Brd1[10];

    WORD Segment_0_Data[1024];
    WORD Segment_1_Data[1024];
    WORD Segment_2_Data[1024];
    WORD Segment_3_Data[1024];
    WORD Segment_4_Data[1024];
    WORD Segment_5_Data[1024];

    double pi = 3.14159265358979;
    DWORD i;
    DWORD MemoryDepth = 1024; // Fill up some arrays

    for (i=0; i < (MemoryDepth); i++) {      // NOT EXACT FIT FOR NON-INTEGRAL MEMORY
VALUES
        Segment_0_Data[i] = 2047;           // Created 0V PAD
        Segment_1_Data[i] = ceil( 2047.0 - 2047.0*cos( 2.0*pi*i/(64) ) ); // 31.25 MHz
        Segment_2_Data[i] = ceil( 2047.0 - 2047.0*cos( 2.0*pi*i/(32) ) ); // 62.5 MHz
        Segment_3_Data[i] = ceil( 2047.0 - 2047.0*cos( 2.0*pi*i/(16) ) ); // 125 MHz
        Segment_4_Data[i] = ceil( 2047.0 - 2047.0*cos( 2.0*pi*i/(128) ) ); // 15.625 MHz
        Segment_5_Data[i] = 2047;         // Created 0V PAD
    }

    Segment_0_Data[8] = Segment_0_Data[8] | 0x3000; // Add both Markers to Seg 0

// Create Segment #0
    SegmentsList_Brd1[0].SegmentNum      = 0;
    SegmentsList_Brd1[0].SegmentPtr      = Segment_0_Data;
    SegmentsList_Brd1[0].NumPoints       = 128; //
    SegmentsList_Brd1[0].NumLoops        = 0; // Loop Count
    SegmentsList_Brd1[0].BeginPadVal     = 2047; // n/a
    SegmentsList_Brd1[0].EndingPadVal    = 2047; // n/a
    SegmentsList_Brd1[0].TrigEn          = 0; // Trigger for Next Segment
    SegmentsList_Brd1[0].NextSegNum      = 1; // Jumps to 1

// Create Segment #1
    SegmentsList_Brd1[1].SegmentNum      = 1;
    SegmentsList_Brd1[1].SegmentPtr      = Segment_1_Data;
    SegmentsList_Brd1[1].NumPoints       = 128; //
    SegmentsList_Brd1[1].NumLoops        = 0; // Loop Count
    SegmentsList_Brd1[1].BeginPadVal     = 2047; // n/a
    SegmentsList_Brd1[1].EndingPadVal    = 2047; // n/a
    SegmentsList_Brd1[1].TrigEn          = 0; // Trigger for Next Segment
    SegmentsList_Brd1[1].NextSegNum      = 2; // Jumps to 2

// Create Segment #2
    SegmentsList_Brd1[2].SegmentNum      = 2;
    SegmentsList_Brd1[2].SegmentPtr      = Segment_2_Data;

```

```

SegmentsList_Brd1[2].NumPoints      = 128;    //
SegmentsList_Brd1[2].NumLoops       = 0;      // Loop Count
SegmentsList_Brd1[2].BeginPadVal    = 2047;   // n/a
SegmentsList_Brd1[2].EndingPadVal   = 2047;   // n/a
SegmentsList_Brd1[2].TrigEn         = 0;      // Trigger for Next Segment
SegmentsList_Brd1[2].NextSegNum     = 3;      // Jumps to 3

// Create Segment #3
SegmentsList_Brd1[3].SegmentNum     = 3;
SegmentsList_Brd1[3].SegmentPtr     = Segment_3_Data;
SegmentsList_Brd1[3].NumPoints      = 128;    //
SegmentsList_Brd1[3].NumLoops       = 0;      // Loop Count
SegmentsList_Brd1[3].BeginPadVal    = 2047;   // n/a
SegmentsList_Brd1[3].EndingPadVal   = 2047;   // n/a
SegmentsList_Brd1[3].TrigEn         = 0;      // Trigger for Next Segment
SegmentsList_Brd1[3].NextSegNum     = 4;      // Jumps to 4

// Create Segment #4
SegmentsList_Brd1[4].SegmentNum     = 4;
SegmentsList_Brd1[4].SegmentPtr     = Segment_4_Data;
SegmentsList_Brd1[4].NumPoints      = 128;    //
SegmentsList_Brd1[4].NumLoops       = 0;      // Loop Count
SegmentsList_Brd1[4].BeginPadVal    = 2047;   // n/a
SegmentsList_Brd1[4].EndingPadVal   = 2047;   // n/a
SegmentsList_Brd1[4].TrigEn         = 0;      // Trigger for Next Segment
SegmentsList_Brd1[4].NextSegNum     = 5;      // Jumps to 5

// Create Segment #5
SegmentsList_Brd1[5].SegmentNum     = 5;
SegmentsList_Brd1[5].SegmentPtr     = Segment_5_Data;
SegmentsList_Brd1[5].NumPoints      = 128;    //
SegmentsList_Brd1[5].NumLoops       = 0;      // Loop Count
SegmentsList_Brd1[5].BeginPadVal    = 2047;   // n/a
SegmentsList_Brd1[5].EndingPadVal   = 2047;   // n/a
SegmentsList_Brd1[5].TrigEn         = 1;      // Trigger for Next Segment
SegmentsList_Brd1[5].NextSegNum     = 0;      // Jumps back to 0

// ##### SPECIAL TESTING ##### //

// INITIALIZE BRD 1
dal2000_Open(1);
dal2000_SetTriggerMode(1,0,0);
// dal2000_SetClock(1,100000000);

// DOWNLOAD BRD#1 AND ENABLE
// dal2000_CreateSegments(DWORD CardNum, DWORD ChanNum, DWORD
NumSegments, PVOID PtrToSegmentsList);
dal2000_CreateSegments(1,1,6,SegmentsList_Brd1);

// dal2000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol);
dal2000_SetTriggerMode(1,2,0); // START OUTPUT 1
// dal2000_SetTriggerMode(1,0,0); // STOP OUTPUT 1

```

4.3.2.10 da14000_Set_Atten() [TBD]

Description

This function call sets the amount of attenuation of the selected channel. The step size is 0.5dB. Typical insertion loss is 1.3dB. Only the first 6 bits of the "Atten_Value" are used, making the maximum amount of attenuation of 31.5dB (+ insertion loss).

Declaration

```
void da14000_Set_Atten(DWORD CardNum, DWORD ChanNum, DWORD Atten_Value)
```

Parameters

```
CardNum:      1 <= CardNum <= 4
ChanNum:      0x01, 0x02, for channels 1,2 [DA14000]
Atten_Value:  0 <= 63;
```

Return Value:

none.

Example

```
da14000_Set_Atten(1,3,30); // Sets Channel 1, Card 1, to 15dB attenuation.
```

4.3.2.11 da14000_UpdateSegmentCmds () [TBD]**Description**

This function call works that same as “da14000_CreateSegments ()” except that it does not download the data from system memory to card memory. Only the sequence commands are downloaded to the card’s memory. This saves time when the user wants to change the order of the segments because the segment data does not have to be updated. (The micro-commands tell the memory sequencer how many times to loop, when to jump, etc.)

Declaration

```
void da14000_UpdateSegmentCmds(DWORD CardNum,
                               DWORD ChanNum,
                               DWORD NumSegments,
                               PVOID PtrToSegmentsList);
```

Parameters

```
CardNum:      1 <= CardNum <= 4
ChanNum:      1 <= CardNum <= 4
```

NumSegments: Number of segment structures (see below) which user has defined and wants to use.

PtrToSegmentsList: Pointer to user array with each element with structure defined as shown below.

```
typedef struct
{
    DWORD   SegmentNum;    // Current Segment Number
    PVOID   SegmentPtr;   // Pointer to current user segment
                                // ==> elements of one dimensional array must
                                // be of type DWORD
    DWORD   NumPoints;    // Number of points in segment
    DWORD   NumLoops;     // Number of times to repeat segment (applies
                                // to next segment)
    DWORD   BeginPadVal;  // Reserved for future use.
    DWORD   EndingPadVal; // Reserved for future use.
    DWORD   TrigEn;      // If > 0 then wait for trigger before going to
                                // next segment.
    DWORD   NextSegNum;   // Next segment to jump to after completion
                                // of current segment activities
} SegmentStruct;
```

**** Note that a segment is determined to be a triggered segment by the previous segment. So setting Segment 5 as triggered will stop the sequence after Segment 5 has executed and will wait for trigger event before "NextSegNum" is started.

The first segment is a special case and is determined by default as a triggered type if SetTriggerMode() is set to "mode=2". The user in this case may use an external trigger or a "soft" trigger to initiate the output process.

Return Value:

none.

Example

See da14000_CreateSegments() above for example.

4.4 Programming Examples

4.4.1 Using Windows 7 64-bit DLL

Example Program

```
// USER EXAMPLE PROGRAM - MAKES CALLS TO "DA12000_DLL64.dll"

#include <windows.h>
#include <winioctl.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>
#include <memory.h>

#include "da12000_dll64_test.h"
#include "da12000_dll64_import.h"
#include "bits.h"

//#####

int main(void) { //(int argc, char *argv[]) {

    DWORD error = 0;
    DWORD CardNum = 1;
    DWORD* TempArray = NULL;
    TempArray = new DWORD[2097152]; //[128];//[2097152];//[1048576];
    DWORD MemoryDepth = 128; //1048576; // MUST BE MULTIPLES OF 64
    double pi = 3.14159265;

    // DISPLAY BANNER
    printf("\nCHASE-SDK Test Application 1.0\n");
    printf("Chase Scientific Company, 2010\n");
    printf("Supporting the DA12000-12-16M-PCI Card \n\n");

    // OPEN DA12000 CARD
    error = da12000_Open(CardNum);
    if (error == 0) printf("DA12000 Opened Successfully for CardNum=%d.\n\n", CardNum);
    else {
        printf("Device Not Found. Code=%d.\n\n", error);
        return error;
    }
}
```

```

// INITIALIZE BOARD (very important)
dal2000_SetTriggerMode(CardNum,0,0); //dal2000_SetTriggerMode(DWORD CardNum, BYTE
Mode, BYTE ExtPol);
printf("dal2000_SetTriggerMode(CardNum,0,0);\n");
printf("==> Initialize Board.\n\n");

// PUT WAVEFORM INTO ARRAY
for (DWORD i=0; i < MemoryDepth; i++) {
    TempArray[i] = ceil( 2047.5 - 2047.5*cos(2*pi*i/(32)) );
}
printf("Creating Sinewave in TempArray[].\n\n");

// Add Marker if desired BEFORE waveform is uploaded.
// TempArray[4] = TempArray[4] | BIT12 | BIT13; // DA12000
TempArray[8] = TempArray[8] | BIT12 | BIT13; // DA14000

// CREATE SINGLE SEGMENT WITH INFINITE LOOP (UPLOADS DATA TO CARD)
dal2000_CreateSingleSegment(1, 1, MemoryDepth, 0, TempArray, 0);
printf("dal2000_CreateSingleSegment(1, 1, MemoryDepth, 0, TempArray, 0);\n");
printf("==> Upload Waveform Data in Single Segment Mode.\n\n");

// OUTPUT DATA
dal2000_SetTriggerMode(CardNum,1,0);
printf("dal2000_SetTriggerMode(CardNum,1,0);\n");
printf("==> Outputting Waveform.\n\n");

// WAIT FOR KEY HIT
printf("Hit Key to Exit.\n\n");
getchar();

// SHUT DOWN OUTPUT (remove // to shut down)
dal2000_SetTriggerMode(CardNum,0,0);
printf("dal2000_SetTriggerMode(CardNum,0,0);\n");
printf("Waveform Output Shut OFF.\n\n", CardNum);

// CLOSE DRIVER
dal2000_Close(CardNum); // Closes brd# CardNum
printf("DA12000 Closed for CardNum=%d.\n\n", CardNum);

delete [] TempArray;
TempArray = NULL;

// WAIT FOR KEY HIT
printf("Hit Key to Exit.\n\n");
getchar();

return 0;
}

```

Header File (for Reference)

```

//-----
#ifndef dal2000_dll64_importH
#define dal2000_dll64_importH
//-----

//-----
// USER ROUTINES
//-----

```

```

#define IMPORT extern "C" __declspec(dllimport)

// DA12000 prototypes
IMPORT DWORD dal2000_CountCards(void);
IMPORT DWORD dal2000_Open(DWORD CardNum);
IMPORT DWORD dal2000_Close(DWORD CardNum);

IMPORT void dal2000_SetClock(DWORD CardNum, DWORD Frequency);

IMPORT void dal2000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol);
IMPORT void dal2000_SetSoftTrigger(DWORD CardNum);
IMPORT void dal2000_SetOffset(DWORD CardNum, DWORD ChanNum, int Mode, int Offset);

IMPORT void dal2000_CreateSingleSegment(DWORD CardNum, DWORD ChanNum, DWORD NumPoints,
DWORD NumLoops, PVOID UserArrayPtr, DWORD TrigEn);
IMPORT void dal2000_CreateSegments(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList);
IMPORT void dal2000_UpdateSegmentCmds(DWORD CardNum, DWORD ChanNum, DWORD NumSegments,
PVOID PtrToSegmentsList);

//-----
// USER ROUTINES (DA14000 calls really calls to same DA12000 DLL)
//-----

dal4000_CountCards() {return dal2000_CountCards();}
dal4000_Open(DWORD CardNum) {return dal2000_Open(CardNum);}
dal4000_Close(DWORD CardNum) {return dal2000_Close(CardNum);}

dal4000_SetClock(DWORD CardNum, DWORD Frequency) {
    dal2000_SetClock(CardNum, Frequency); return (0);
}

void dal4000_SetTriggerMode(DWORD CardNum, BYTE Mode, BYTE ExtPol) {
    dal2000_SetTriggerMode(CardNum, Mode, ExtPol);
}

void dal4000_SetSoftTrigger(DWORD CardNum) {
    dal2000_SetSoftTrigger(CardNum);
}

void dal4000_SetOffset(DWORD CardNum, DWORD ChanNum, int Mode, int Offset) {
    dal2000_SetOffset(CardNum, ChanNum, Mode, Offset);
}

void dal4000_CreateSingleSegment(DWORD CardNum, DWORD ChanNum, DWORD NumPoints, DWORD
NumLoops, PVOID UserArrayPtr, DWORD TrigEn) {
    dal2000_CreateSingleSegment(CardNum, ChanNum, NumPoints, NumLoops, UserArrayPtr,
TrigEn);
}

void dal4000_CreateSegments(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList) {
    dal2000_CreateSegments(CardNum, ChanNum, NumSegments, PtrToSegmentsList);
}

void dal4000_UpdateSegmentCmds(DWORD CardNum, DWORD ChanNum, DWORD NumSegments, PVOID
PtrToSegmentsList) {
    dal2000_UpdateSegmentCmds(CardNum, ChanNum, NumSegments, PtrToSegmentsList);
}

#endif

```

5 MISCELLANEOUS

5.1 Calibration

The DA14000 has no user feature to calibrate. The gains and offsets are calibrated at the factory to be within specifications at 25°C and nominal voltages. However, when using the external clock then you should select jumper U34 to provide the cleanest signal (see clock jumper section 2.4).

5.2 Maintenance

No maintenance is required. However, a yearly calibration is recommended if the user desires to maintain the DA14000 specified accuracy. Call factory for maintainance and/or extended warranty information.

5.3 Changes/Corrections to this manual

Date	Description
07-11-2010	First release.
08-10-2010	Updated various references to UserArrayPtr such that Pointer points to user array of DWORD. Previously was WORD.
12-18-2011	Updated "da14000_CreateSegments()" with better definitions and example

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